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Further assumptions

MFin Econometrics I Session 3: t-distribution, Simple Linear Regression, OLS assumptions and properties of OLS estimators

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What if σ_Y is un-known? (almost always)

• Recall:
$$\bar{Y} \sim N(\mu_Y, \frac{\sigma_Y^2}{n})$$
 and $\frac{\bar{Y} - \mu_Y}{\sigma_Y} \sim N(0, 1)$

- If (Y₁,...,Y_n) are i.i.d. (and 0 < σ²_Y < ∞) then, when n is large, the distribution of Ȳ is well approximated by a normal distribution: Why? CLT
- If $(Y_1, ..., Y_n)$ are independently and identically drawn from a Normal distribution, then for any value of n, the distribution of \overline{Y} is normal: Why? Sums of normal r.v.s are normal
- But we almost never know σ_Y . We use sample standard deviation (s_Y) to estimate the unknown σ_Y
- Consequence of using the sample s.d. in the place of the population s.d. is an increase in uncertainty. *Why?*
 - s_Y/√n is the standard error of the mean : estimate from sample, of st. dev. of sample mean, over all possible samples of size n drawn from the population

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Using s_Y : "estimator" of σ_Y

•
$$s_Y^2 = \frac{1}{\text{sample size-1}} \sum_{i=1}^{\text{sample size}} (Y_i - \bar{Y})^2$$

- Why sample size 1 in this estimator?
- Degrees of freedom (d.f.): the number of *independent observations* available for estimation. Sample size less the number of (linear) parameters estimated from the sample
- Use of an *estimator* (i.e., a random variable) for σ_Y (and thus, the use of an estimator for $\sigma_{\bar{Y}}$) motivates use of the fatter-tailed *t*-distribution in the place of N(0, 1)
- The law of large numbers (LLN) applies to s_Y^2 : s_Y^2 is, in fact, a "sample average" (How?)
- LLN: If sampling is such that (Y₁,...,Y_n) are i.i.d., (and if E(Y⁴) < ∞), then s_Y² converges in probability to σ_Y²:
 s_Y² is an average, not of Y_i, but of its square (hence we need E(Y⁴) < ∞)

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Aside: *t*-distribution probability density

$$f(t) = \frac{\Gamma(\frac{d.f.+1}{2})}{\sqrt{d.f.\pi}\Gamma(\frac{d.f.}{2})} (1 + \frac{t^2}{d.f.})^{-\frac{d.f.+1}{2}}$$

• *d.f.* : Degrees of freedom: the only parameter of the *t*-distribution;

• $\Gamma()$ (Gamma function): $\Gamma(z) = \int_0^\infty t^{z-1} e^{-t} dt$

- Mean: E(t) = 0
- Variance: V(t) = d.f./(d.f. 2) for $d.f. > 2 \ge 1$, converges to 1 as d.f. increases (Compare: N(0, 1))



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t-distribution pdf and CDF: d.f.=3



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t - statistic

$$t_{d.f.} = \frac{\bar{Y} - \mu}{s_Y / \sqrt{n}} \qquad d.f. = n - 1$$

- test statistic for the sample average same form as z-statistic: Mean 0, Variance $\rightarrow 1$
- If the r.v. Y is is normally distributed in population, the test-statistic above for \bar{Y} is t-distributed with d.f. = n 1 degrees of freedom

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t - distribution, table and use



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$t \to \text{SND}$

- If d.f. is moderate or large (> 30, say) differences between the *t*-distribution and N(0, 1) critical values are negligible
- Some 5% critical values for 2-sided tests:

degree of freedom	5%t-distribution critical value
10	2.23
20	2.09
30	2.04
60	2.00
∞	1.96



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Comments on t distribution, contd.

- The t distribution is only relevant when the sample size is small. But then, for the t distribution to be correct, the populn. distrib. of Y must be Normal Why?
 - The popln r.v. (\bar{Y}) must be Normally distributed for the test-statistic (with σ_Y estimated by s_Y) to be *t*-distributed
 - If sample size small, CLT does not apply; the popln distrib. of Y must be Normal for the popln. distrib. of \overline{Y} to be Normal (sum of Normal r.v.s is Normal)
- So if sample size small and σ_Y estimated by s_Y , then test-statistic to be *t*-distributed if popln. is Normally distributed
- If sample size large (e.g., > 30), the popln. distrib. of \overline{Y} is Normal irrespective of distrib. of Y - CLT (we saw that as d.f. increases, distrib. of $t_{d.f.}$ converges to N(0, 1))
- Finance / Management data: Normality assumption dubious. e.g., earnings, firm sizes etc.

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Comments on t distribution, contd.

- So, with large samples,
- \bullet or, with small samples, but with σ known, and a normal population distribution

$$Pr(-z_{\alpha/2} \le \frac{\bar{Y} - \mu}{\sigma/\sqrt{n}} \le z_{\alpha/2}) = 1 - \alpha$$
$$Pr(\bar{Y} - z_{\alpha/2}\frac{\sigma}{\sqrt{n}} \le \mu \le \bar{Y} + z_{\alpha/2}\frac{\sigma}{\sqrt{n}}) = 1 - \alpha$$
$$Pr(\bar{Y} - 1.96\frac{\sigma}{\sqrt{n}} \le \mu \le \bar{Y} + 1.96\frac{\sigma}{\sqrt{n}}) = 0.95$$

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Comments on t distribution, contd.

- With small samples (< 30 d.f.),
- drawn from an approximately normal population distribution,
- with the unknown σ estimated with s_Y ,

• for test statistic
$$\frac{\bar{Y}-\mu}{s_Y/\sqrt{n}}$$
:

$$Pr(\bar{Y} - t_{d.f.,\alpha/2}\frac{s_Y}{\sqrt{n}} \le \mu \le \bar{Y} + t_{d.f.,\alpha/2}\frac{s_Y}{\sqrt{n}}) = 1 - \alpha$$

Q: What is $t_{d.f.,\alpha/2}$?

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Simple linear regression model

Population Linear Regression Model: Bivariate

 $Y = \beta_0 + \beta_1 X + u$

- Interested in conditional probability distribution of Y given X
- Theory / Model : the conditional mean of Y given the value of X is a linear function of X
 - X: the independent variable or regressor
 - Y : the dependent variable
 - β_0 : intercept
 - β_1 : slope
 - u: regression disturbance, which consists of effects of factors other than X that influence Y, as also measurement errors in Y

• n: sample size, $Y_i = \beta_0 + \beta_1 X_i + u_i$ $i = 1, \cdots, n$

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Linear Regression Model - Issues

- Issues in estimation and inference for linear regression estimates are, at a general level, the same as the issues for the sample mean
- Regression coefficient is just a glorified mean
- Estimation questions:
 - How can we estimate our model? i.e., "draw" a line/plane/surface through the data ?
 - Advantages / disadvantages of different methods ?
- Hypothesis testing questions:
 - How do we test the hypothesis that the population parameters are *zero*?
 - Why test if they are zero?
 - How can we construct confidence intervals for the parameters?

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Regression Coefficients of the Simple Linear Regression Model

- How can we estimate β_0 and β_1 from data?
 - Y is the ordinary least squares (OLS) estimator of μ_Y :
 - Can show that \overline{Y} solves:

$$min_X \sum_{i=1}^n (Y_i - X)^2$$

• By analogy, OLS estimators of the unknown parameters β_0 and β_1 , solve:

$$min_{\hat{\beta}_0, \hat{\beta}_1} \sum_{i=1}^n (Y_i - (\hat{\beta}_0 + \hat{\beta}_1 X_i))^2$$

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Simple linear regression model

OLS in pictures (3)Y True model: $Y = \beta_0 + \beta_1 X + u$ Fitted line: $\hat{Y} = \hat{\beta}_0 + \hat{\beta}_1 X$ $\hat{\hat{Y}}_n = \hat{\beta}_0 + \hat{\beta}_1 X_n$ • Y_n $e_1 = Y_1 - \hat{Y}_1 = Y_1 - \hat{\beta}_0 - \hat{\beta}_1 X_1$ $\widetilde{\hat{Y}_1} = \hat{\beta}_{0} + \hat{\beta}_1 X_1$ $\hat{\beta}_{n}$

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OLS method of obtaining regression coefficients

- The sum : $e_1^2 + ... + e_n^2$, is the Residual Sum of Squares (RSS), a measure of total *error*
 - RSS is a function of both $\hat{\beta}_0$ and $\hat{\beta}_1$ (How?)

RSS =
$$(Y_1 - \hat{\beta}_0 - \hat{\beta}_1 X_1)^2 + ... + (Y_n - \hat{\beta}_0 - \hat{\beta}_1 X_n)^2$$

= $\sum_{i=1}^n (Y_i - \hat{\beta}_0 - \hat{\beta}_1 X_i)^2$

• Idea: Find values of $\hat{\beta}_0$ and $\hat{\beta}_1$ that minimise RSS • $\frac{\partial RSS(\cdot)}{\partial \hat{\beta}_0} = -2\sum (Y_i - \hat{\beta}_0 - \hat{\beta}_1 X_i) = 0$ • $\frac{\partial RSS(\cdot)}{\partial \hat{\beta}_1} = -2\sum X_i (Y_i - \hat{\beta}_0 - \hat{\beta}_1 X_i) = 0$

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19/41

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Ordinary Least Squares, contd.

•
$$\frac{\partial RSS}{\partial \hat{\beta}_0} = 0$$
 and $\frac{\partial RSS}{\partial \hat{\beta}_1} = 0$

• Solving these two equations together:

•
$$\hat{\beta}_1 = \frac{\frac{1}{n}\sum(X_i - \bar{X})(Y_i - \bar{Y})}{\frac{1}{n}\sum(X_i - \bar{X})^2} = \frac{\sum(X_i - \bar{X})(Y_i - \bar{Y})}{\sum(X_i - \bar{X})^2} = \frac{Cov(X,Y)}{Var(X)}$$

• $\hat{\beta}_0 = \bar{Y} - \hat{\beta}_1 \bar{X}$

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Linear Regression Model: Interpretation

• Exercise



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21/41

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Linear regression model: Evaluation

Measures of Fit (i): Standard Error of the Regression (SER) and Root Mean Squared Error (RMSE)

- Standard error of the regression (SER) is an estimate of the dispersion (st.dev.) of the distribution of the disturbance term, u;
- Equivalently, of Y, conditional on X
- How close are Y values to \hat{Y} values? can develop confidence intervals around any prediction

•
$$SER = \sqrt{\frac{1}{n-2}\sum_{i=1}^{n} (e_i - \bar{e})^2} = \sqrt{\frac{1}{n-2}\sum_{i=1}^{n} e_i^2}$$

- SER converges to root mean squared error (RMSE)
- $RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (e_i \bar{e})^2} = \sqrt{\frac{1}{n} \sum_{i=1}^{n} e_i^2}$
- RMSE denominator has n SER has (n-2)Why?

• Why?

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coordinationSER
coordinationOLS Properties
coordinationFurther assumptions
coordinationLinear regression model:Evaluation

Measures of Fit (ii): R^2

- How much of the variance in Y can we explain with our model?
- Without the model, the best estimate of Y_i is the sample mean \bar{Y}
- With the model, the best estimate of Y_i is conditional on X_i and is the fitted value $\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$
- How much does the error in estimate of Y reduce with the model?

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Linear regression model: Evaluation

Goodness of fit

• The model: $Y_i = \hat{Y}_i + e_i$

• Total Sum of Squares (TSS) = Explained Sum of Squares (ESS) + Residual Sum of Squares (RSS)

$$R^{2} = \frac{ESS}{TSS} = \frac{\sum (\hat{Y}_{i} - \bar{Y})^{2}}{\sum (Y_{i} - \bar{Y})^{2}}$$

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Properties of OLS Estimators

After regression estimates

- In practical terms, we wish to:
 - quantify sampling uncertainty associated with $\hat{\beta}_1$
 - use $\hat{\beta}_1$ to test hypotheses such as $\beta_1 = 0$
 - construct confidence intervals for β_1
- all these require knowledge of the sampling distribution of the OLS estimators (based on the probability framework of regression)

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Properties of OLS Estimators

Properties of Estimators and the Least Squares Assumptions

- What kinds of estimators would we like?
- unbiased, efficient, consistent
- Under what conditions can these properties be guaranteed?
- We focus on the sampling distribution of $\hat{\beta}_1$ (Why not $\hat{\beta}_0$?)
 - The results below do hold for the sampling distribution of $\hat{\beta}_0$ too.





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Properties of OLS Estimators



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Properties of OLS Estimators

Assumption 1: E(u|X = x) = 0

- Conditional on X, u does not tend to influence Y either positively or negatively.
- Implication : Either X is not random, or,
- If X is random, it is distributed independently of the disturbance term, u: Cov(X, u) = 0
- This will be true if there are no relevant omitted variables in the regression model (i.e., those that are correlated to X)

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Further assumptions

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Aside: include a constant in the regression

• Suppose
$$E(u_i) = \mu_u \neq 0$$

• Suppose
$$u_i = \mu_u + v_i$$
 where $v_i \sim N(0, \sigma_V^2)$

• Then
$$Y_i = \beta_0 + \beta_1 X_i + v_i + \mu_u = (\beta_0 + \mu_u) + \beta_1 X_i + v_i$$

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Assumption 2: $(X_i, Y_i), i = 1, ..., n$ are i.i.d.

- This arises naturally with simple random sampling procedure
- Because most estimators are linear functions of observations,
- Independence between observations helps in obtaining the sampling distributions of the estimators

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Assumption 3: Large outliers are rare

- A large outlier is an *extreme* value of X or Y
- Technically, $E(X^4) < \infty$ and $E(Y^4) < \infty$
 - Note: If X and Y are bounded, then they have finite fourth moments (income, etc.)
- Rationale : a large outlier can influence the results significantly



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Properties of OLS Estimators

Sampling distribution of $\hat{\beta}_1$

- If the three Least Squares Assumptions (mean zero disturbances, i.i.d. sampling, no large outliers) hold,
- then the exact (finite sample) sampling distribution of $\hat{\beta}_1$ is such that:
 - $\hat{\beta}_1$ is unbiased, that is, $E(\hat{\beta}_1) = \beta_1$
 - $Var(\hat{\beta}_1)$ can be determined
 - Other than its mean and variance, the exact distribution of $\hat{\beta_1}$ is complicated and depends on the distribution of (X, u)
 - $\hat{\beta}_1$ is consistent: $\hat{\beta}_1 \rightarrow_p \beta_1$ $plim(\hat{\beta}_1) = \beta_1$
 - So when *n* is large, $\frac{\hat{\beta}_1 \beta_1}{\sqrt{Var(\hat{\beta}_1)}} \sim N(0, 1)$ (by CLT)
- \bullet This parallels the sampling distribution of \bar{Y}

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Properties of OLS Estimators

Mean of the sampling distribution of $\hat{\beta}_1$

- $Y = \beta_0 + \beta_1 X + u$
- unbiasedness

$$\hat{\beta}_1 = \frac{Cov(X,Y)}{Var(X)} = \frac{Cov(X,[\beta_0 + \beta_1 X + u])}{Var(X)}$$

$$= \frac{Cov(X,\beta_0) + Cov(X,\beta_1 X) + Cov(X,u)}{Var(X)}$$

$$= \frac{0 + \beta_1 Cov(X,X) + Cov(X,u)}{Var(X)}$$

$$= \beta_1 + \frac{Cov(X,u)}{Var(X)}$$

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Unbiasedness of $\hat{\beta}_1$

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$$\hat{\beta}_1 = \frac{Cov(X,Y)}{Var(X)} = \beta_1 + \frac{Cov(X,u)}{Var(X)}$$

- To investigate unbiasedness, take Expectation
- $E(\hat{\beta}_1) = \beta_1 + \frac{1}{Var(X)}E(Cov(X, u)) = \beta_1$
 - Expected value of Cov(X, u) is zero (Why?)
- $\hat{\beta}_1$ is an unbiased estimator of β_1

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0000OLS Properties
000000000000Further assumptions
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Homoscedasticity and Normality of residuals

- $\bullet~u$ is homoscedastic
- $u \sim N(0, {\sigma_u}^2)$
- These assumptions are more restrictive
- However, if these assumptions are not violated, then other desirable properties obtain







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Normality of disturbances: histograms of residuals that 'pass' and 'fail'



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Normality of disturbances 2: q-q plots of residuals that 'pass' and 'fail'

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